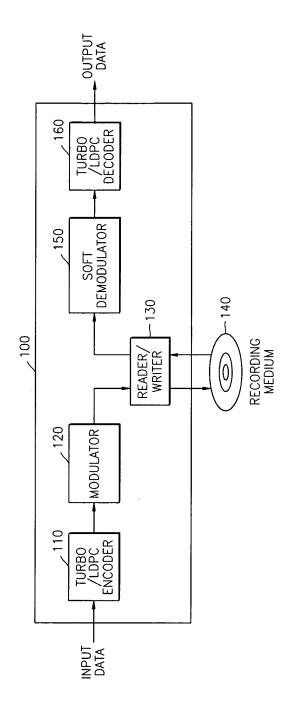
FIG. 1 (PRIOR ART)



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FIG. 2 (PRIOR ART)

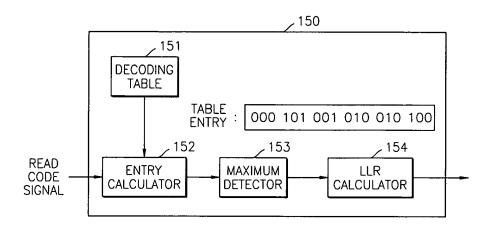


FIG. 3 (PRIOR ART)

	d _k d _{k+1}
1	000 101 001 010 010 100
2	010 010 001 010 010 100
• • •	
5000	000 101 001 010 010 010

FIG. 4 (PRIOR ART)

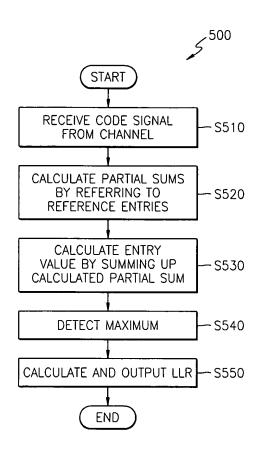
RECEIVED .		: 0 0 0 1 0 1 0 0 1 0 1 0 0 1 0 1 0 0 0 0 0 0		430	CALCULATION -rrrrrrrrrr.
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RECEIVED : CODE SIGNAL		TABLE : ENTRY :		-	CALCULATION .

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APPARATUS
INVENTORS: Sung-hyu HAN et al.

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FIG. 5



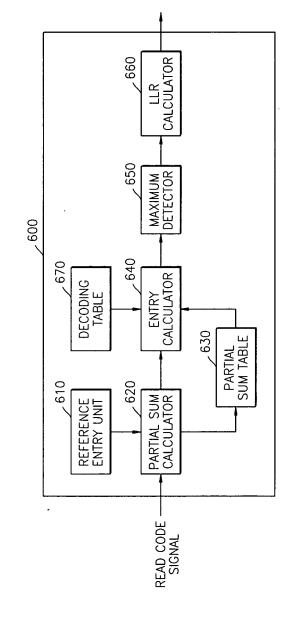
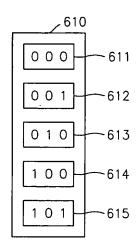


FIG. 6

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SERIAL NO.: DOCKET NO.: 1793.1181

FIG. 7



INVENTORS: Sung-hyu HAN et al.

SERIAL NO.:

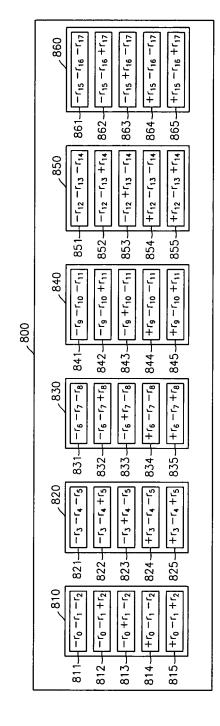
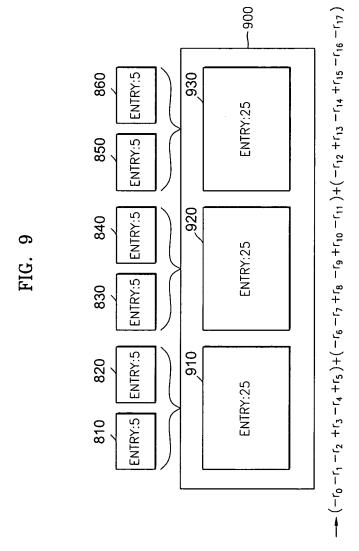
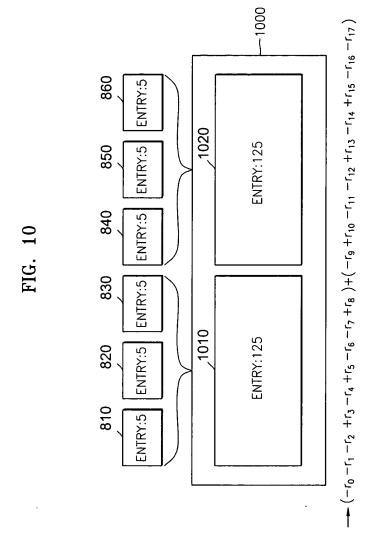


FIG. 8





TITLE: SOFT DEMODULATION METHOD AND APPARATUS

INVENTORS: Sung-hyu HAN et al.

SERIAL NO.:

FIG. 11

